



Submarine Mine Countermeasures



***Presented by
CDR Rich Medley
4 November 99***



Outline

→ **MCM Performance**

- **Submarine MCM**
- **MCM Common Operational Picture
(MCM COP)**
- **Summary**



Mine Countermeasures

Purpose: Allow timely access to areas potentially denied by mines.

Why emphasize Mine Hunting?

- Allows Mine Avoidance if possible.
- Enables Mine Neutralization if necessary.

Elements of Successful Mine Hunting:

- High area coverage rate.
- High probability of finding and calling a mine a mine.
- Low probability of calling a non-mine a mine.



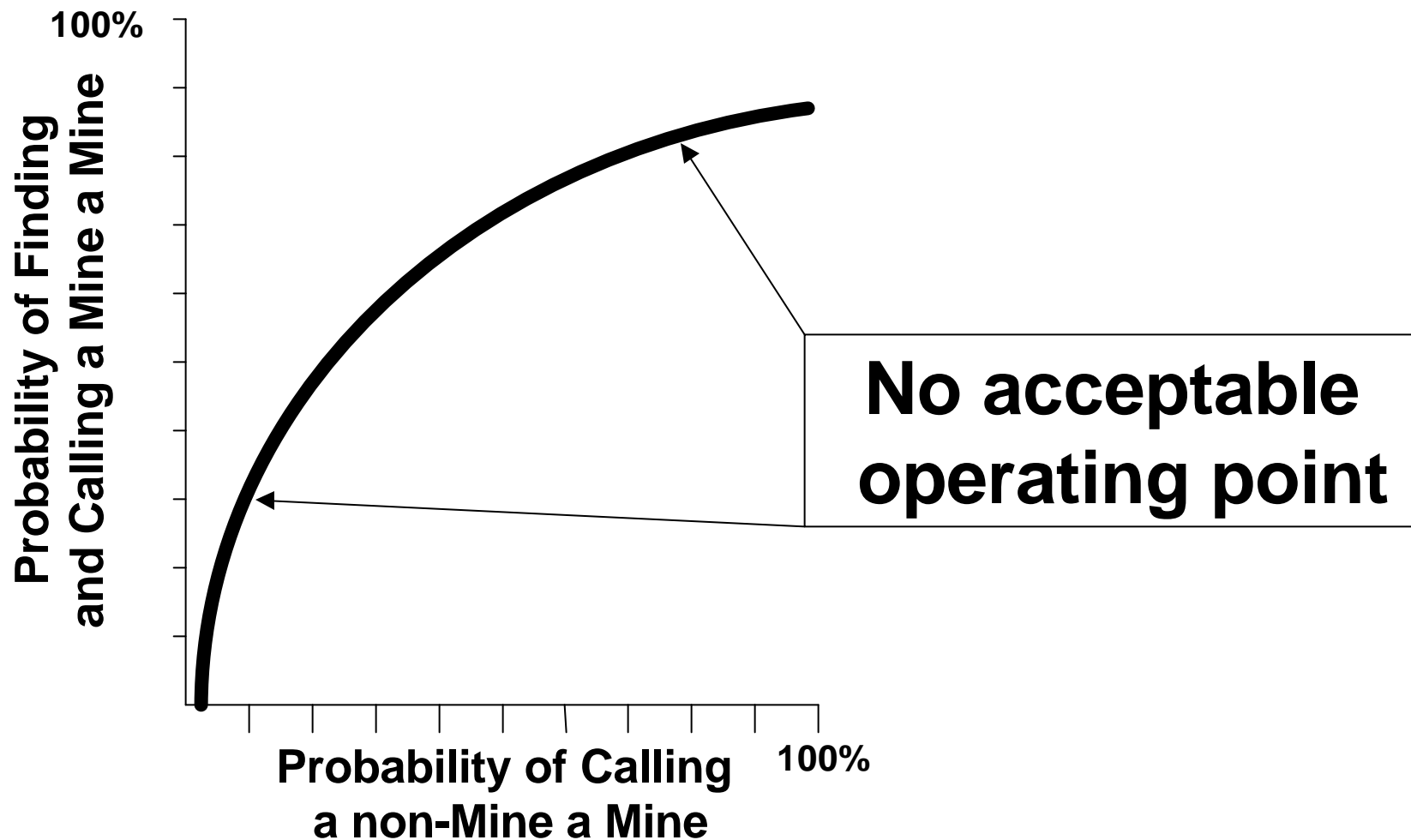
How to Reduce the Timeline?

- **Maximize the area coverage rate without sacrificing the ability to differentiate between a mine and a non-mine (increase the speed of advance, swath size or both).**
- **Improve our ability to differentiate between mines and non-mines.**

Detect® Discriminate® Classify® Identify

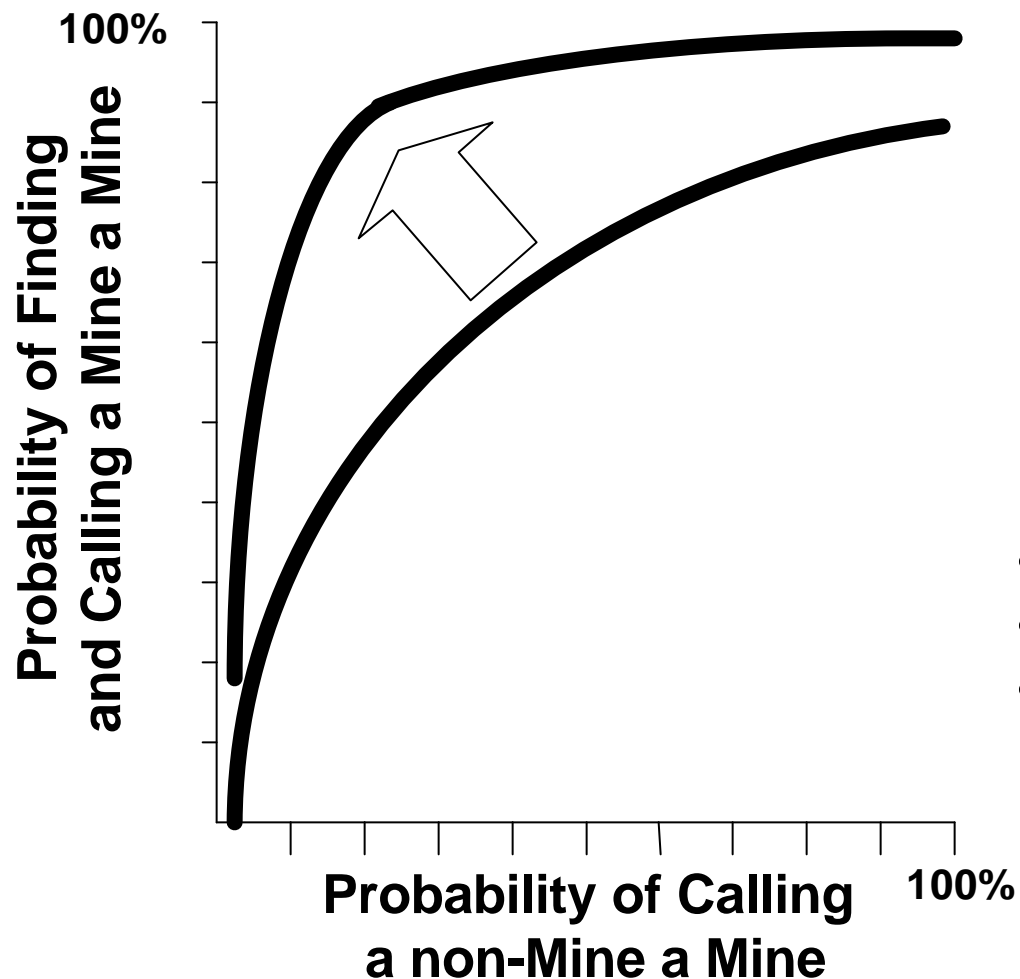


Legacy BQS-15





Improved System Performance Needed



Detection Sensors:

- optimize sonar parameters
- maximize pings on target
- high performance 3D CAD
- null steering reverb suppression

Classification Sensors:

- maximize # of pixels on object
- maximize image contrast
- improve recognition processing



Outline

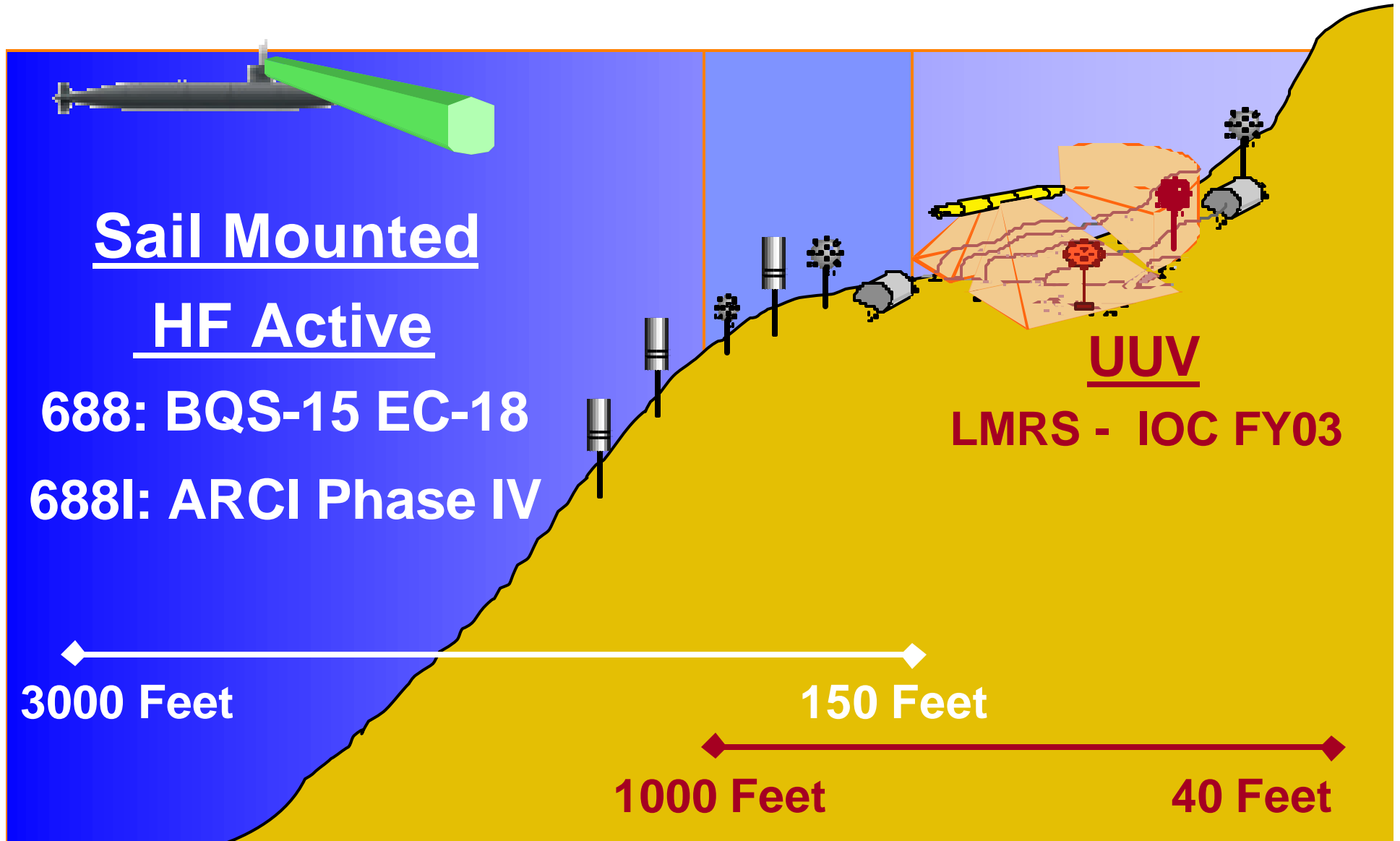
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Submarine MCM Capability





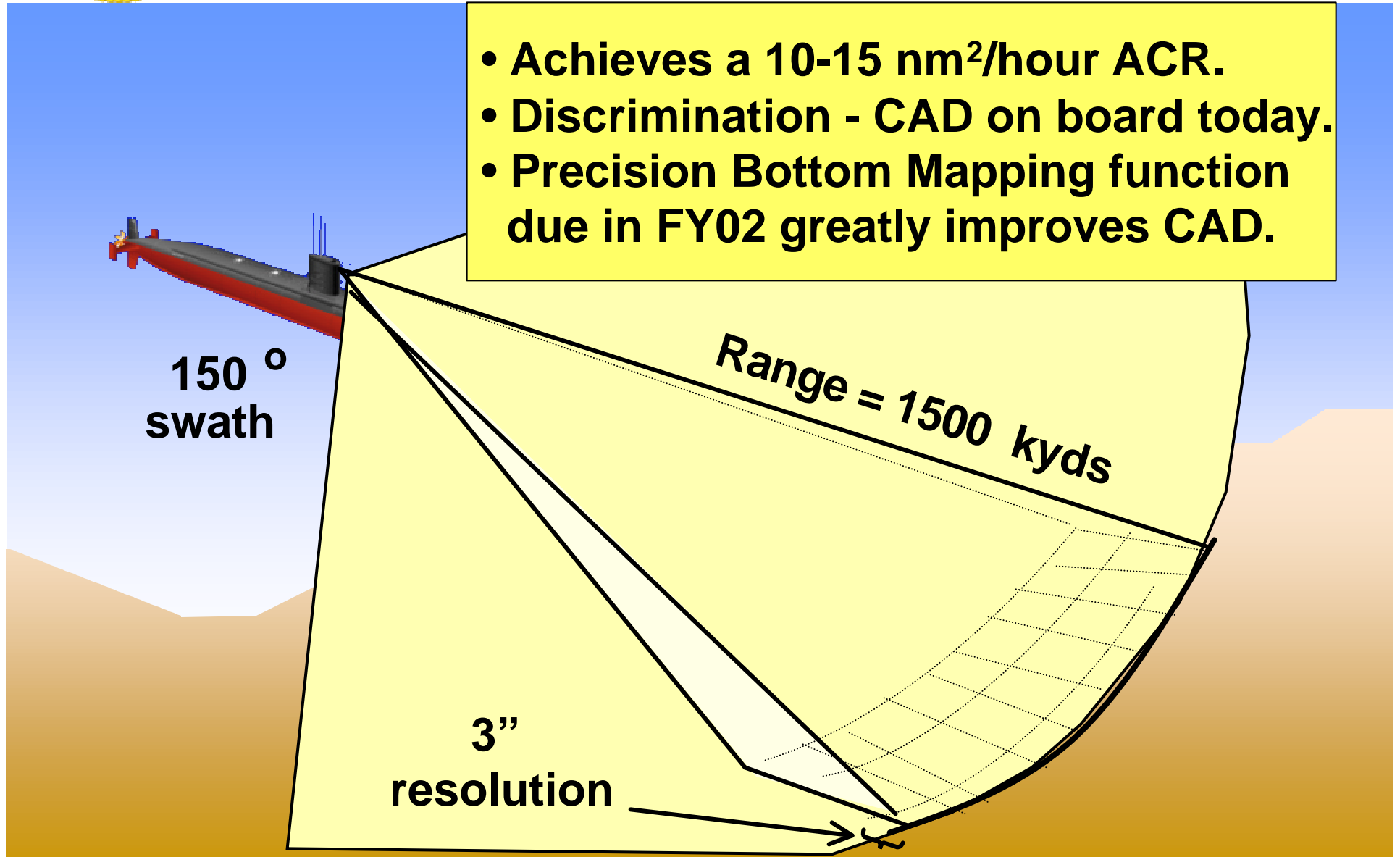
HF Submarine Sonar

- Achieves a 10-15 nm²/hour ACR.
- Discrimination - CAD on board today.
- Precision Bottom Mapping function due in FY02 greatly improves CAD.

**150 °
swath**

Range = 1500 kyds

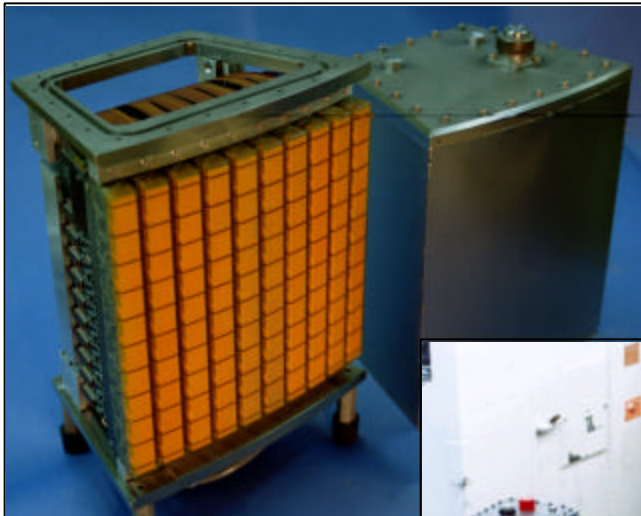
**3"
resolution**





USS Asheville (SSN-758)

EDM Installation



**10x 10 elements
per module**

**8 modules
800 channel receive array**

Sail Mounted



All 688I's - IOC 00

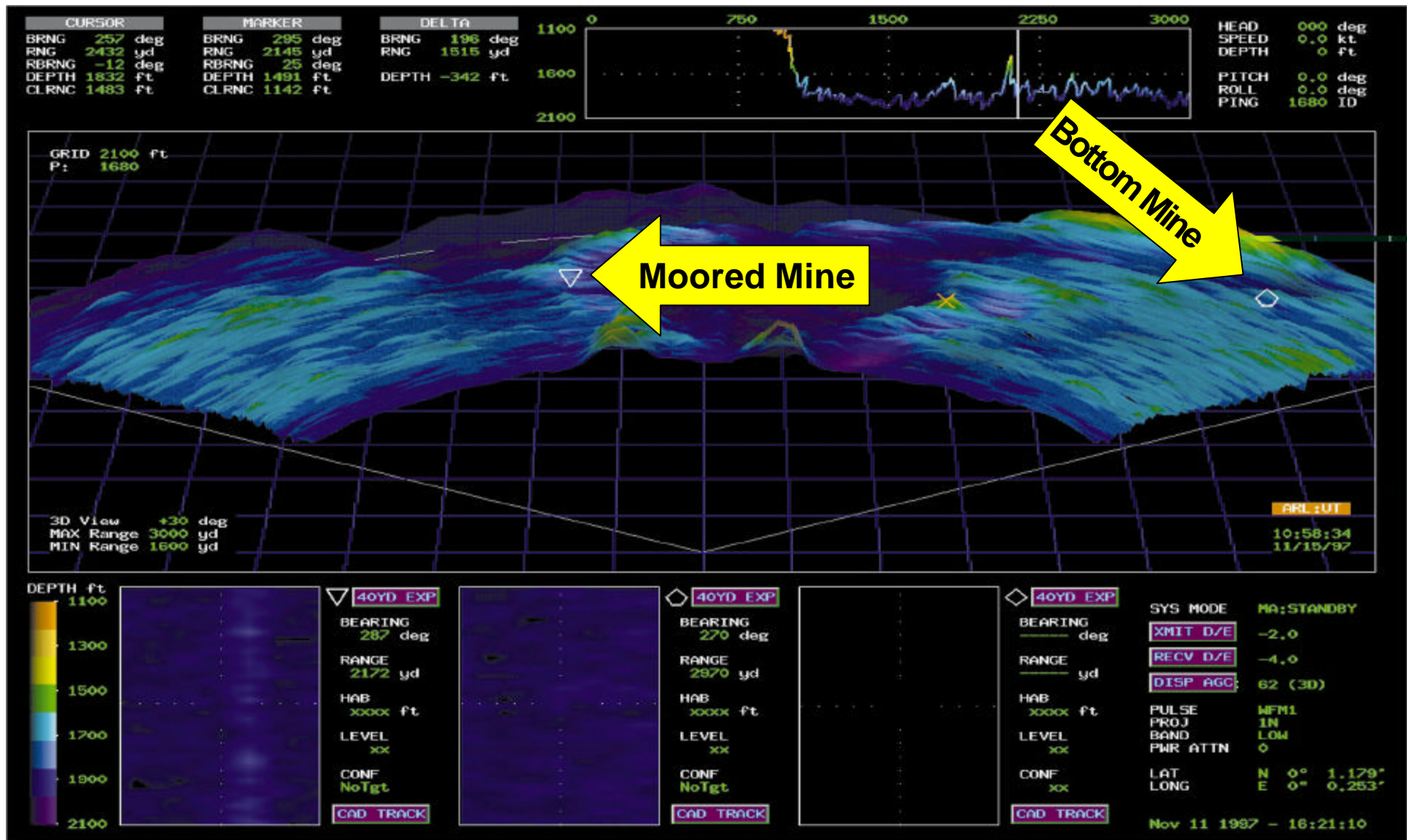
Virginia Class

- **3D CAD**
- **3D Display**
- **Terrain Profiling**





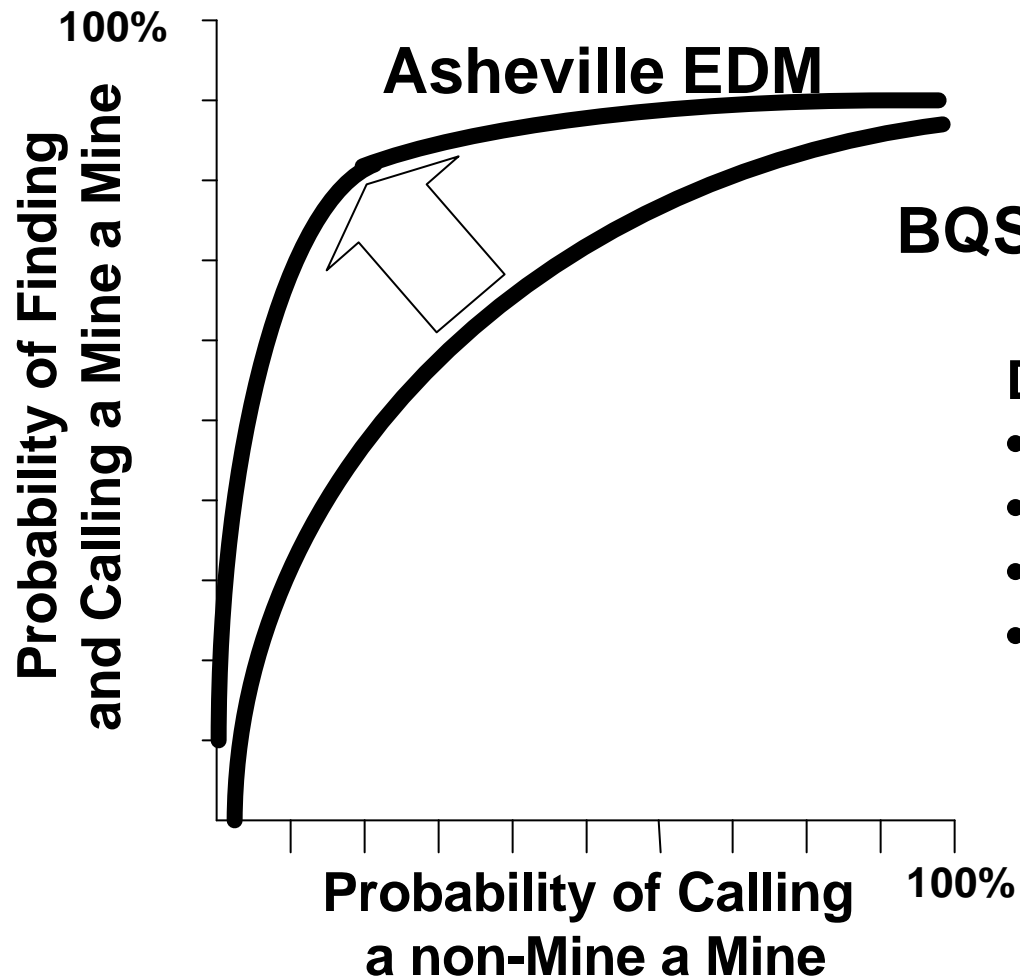
USS Asheville (SSN-758) EDM At-Sea Today





Where We Are Today!

With a 10-15 nm²/hour ACR.



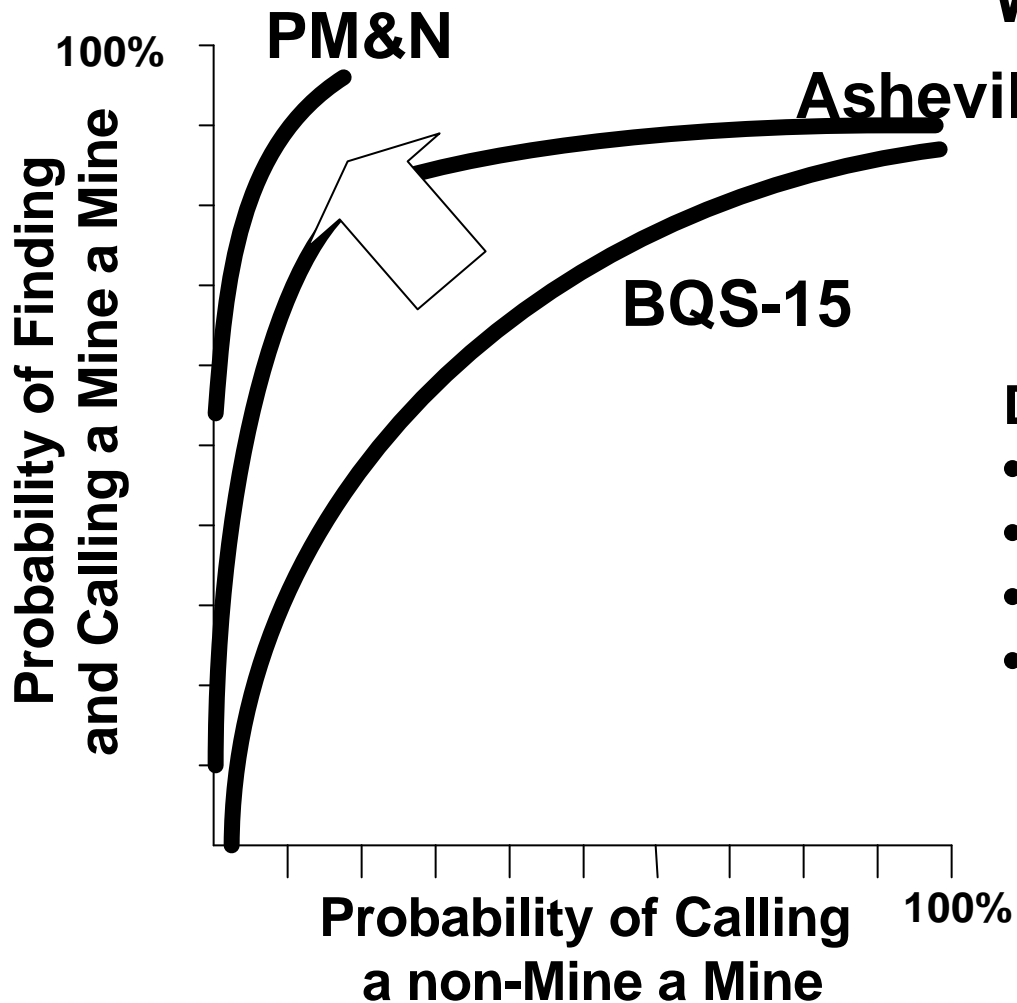
Detection Sensors:

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Where We Are Going!

With a 10-15 nm²/hour ACR.

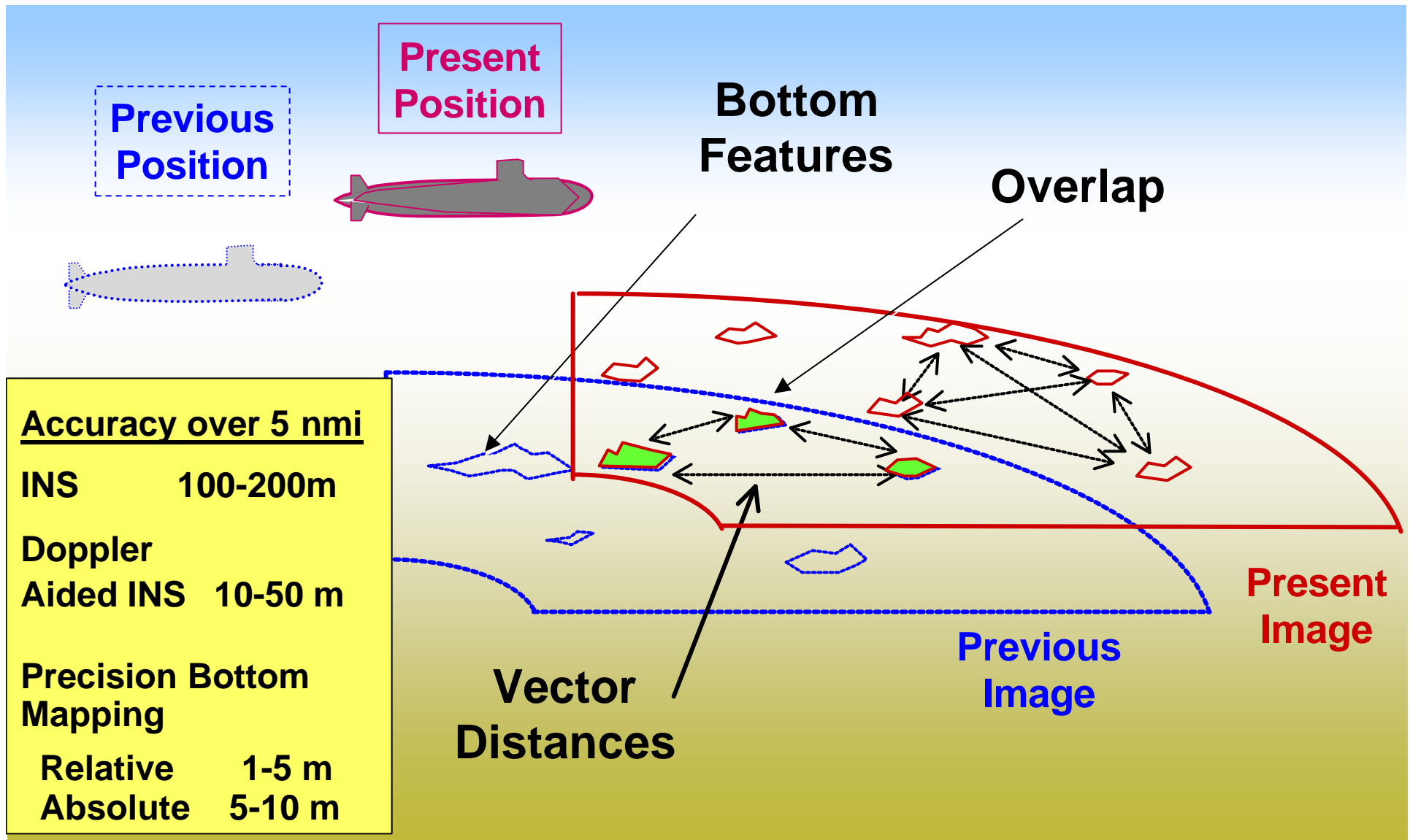


Detection Sensors:

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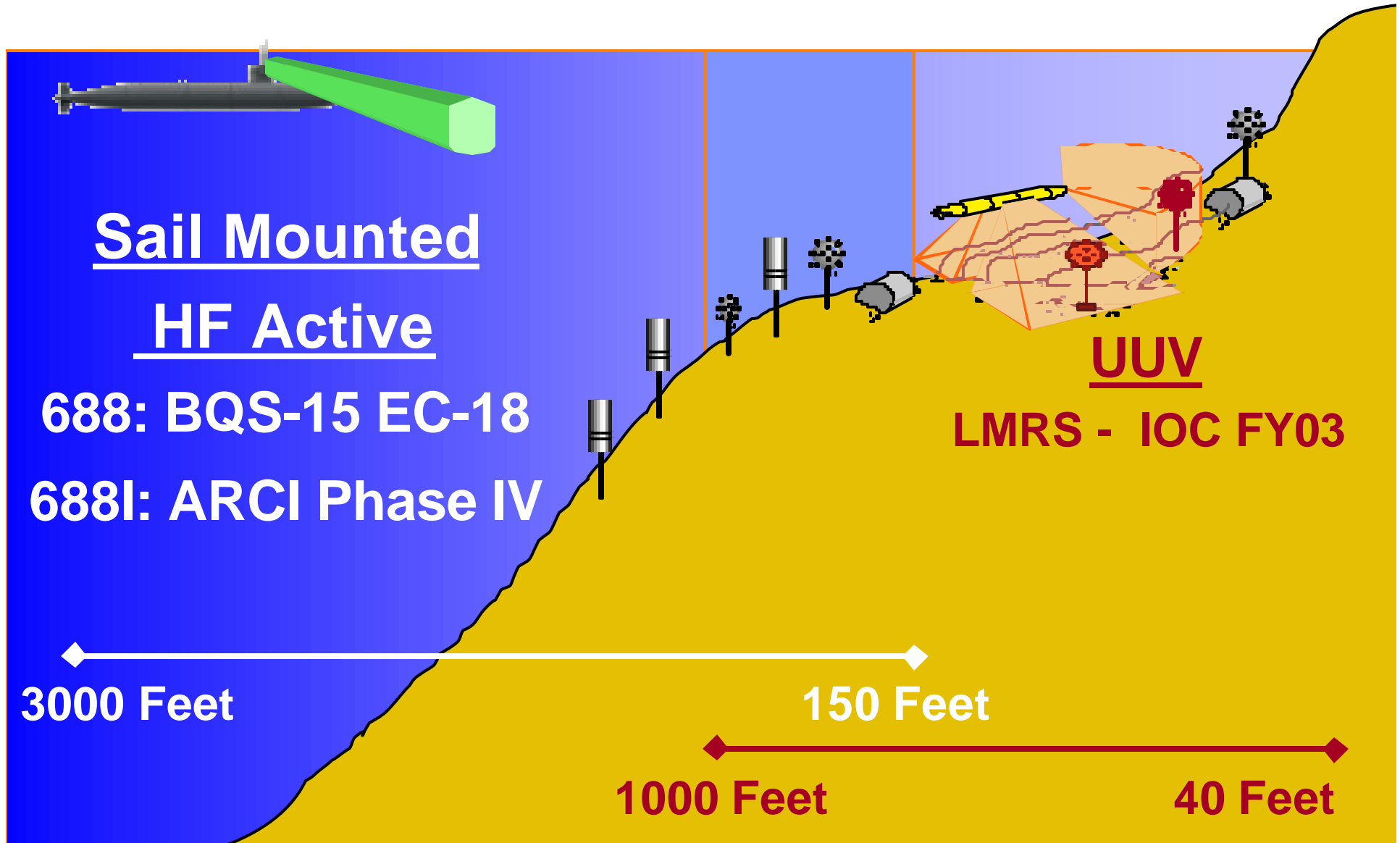


Improved Underwater Navigation





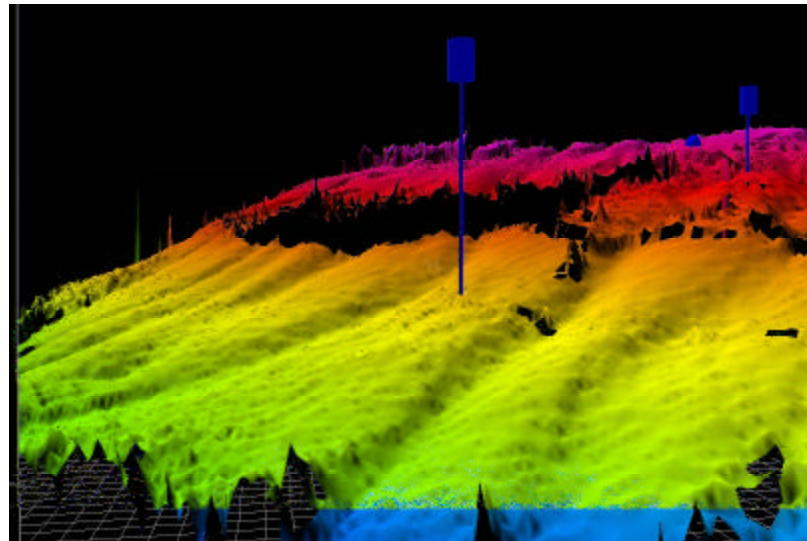
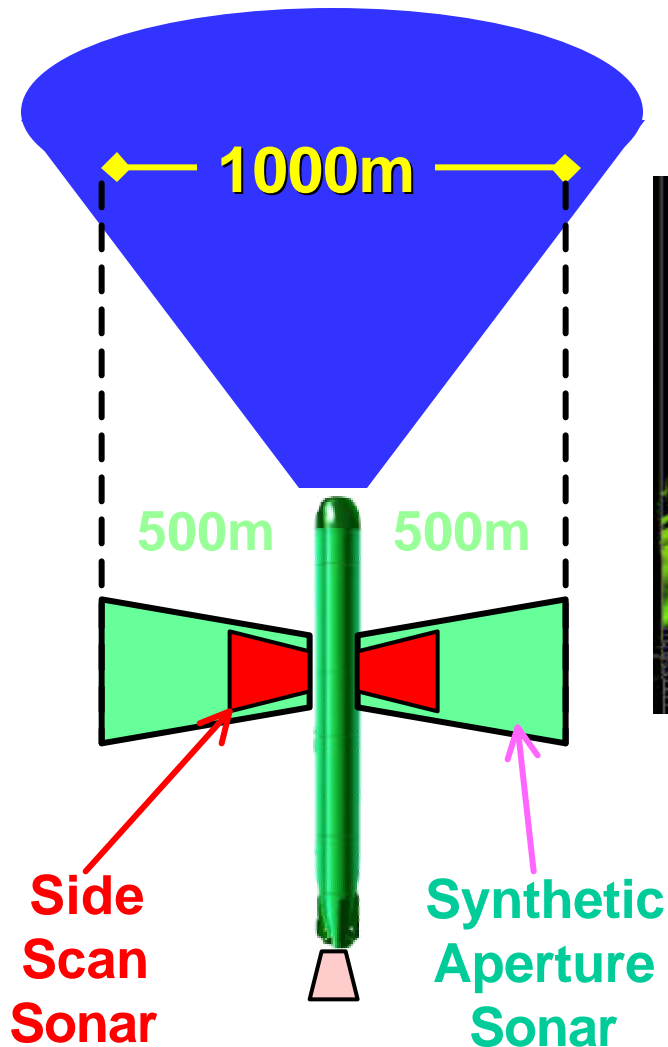
Submarine MCM Capability





Long-Term Mine Reconnaissance System (LMRS)

LMRS with PM&N and SAS

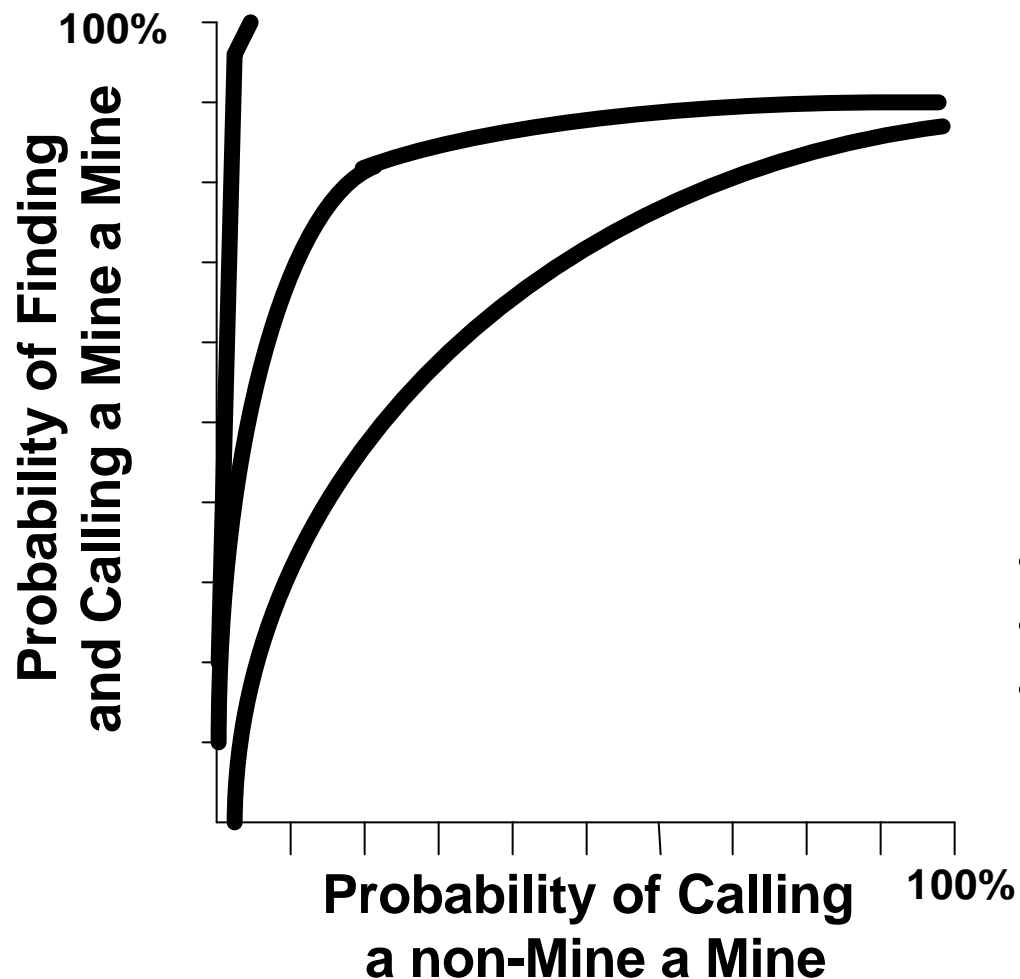


Detect
↓
Discriminate
↓
Classification

- All functions “in stride”
- 2.5 nm²/hr ACR
- Exploit the ALS/SLS combination



An ALS and SLS Combination?



Detection Sensors:

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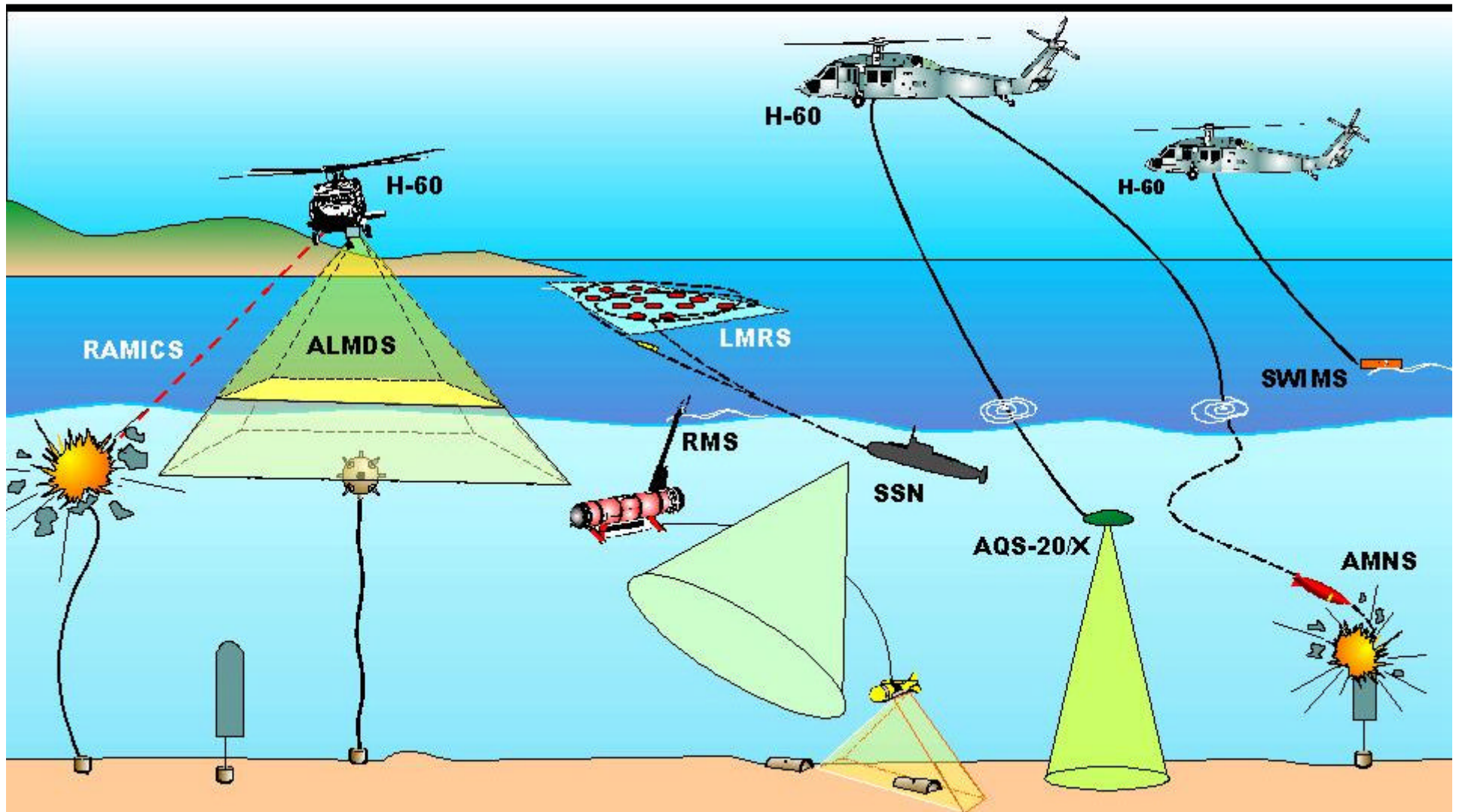
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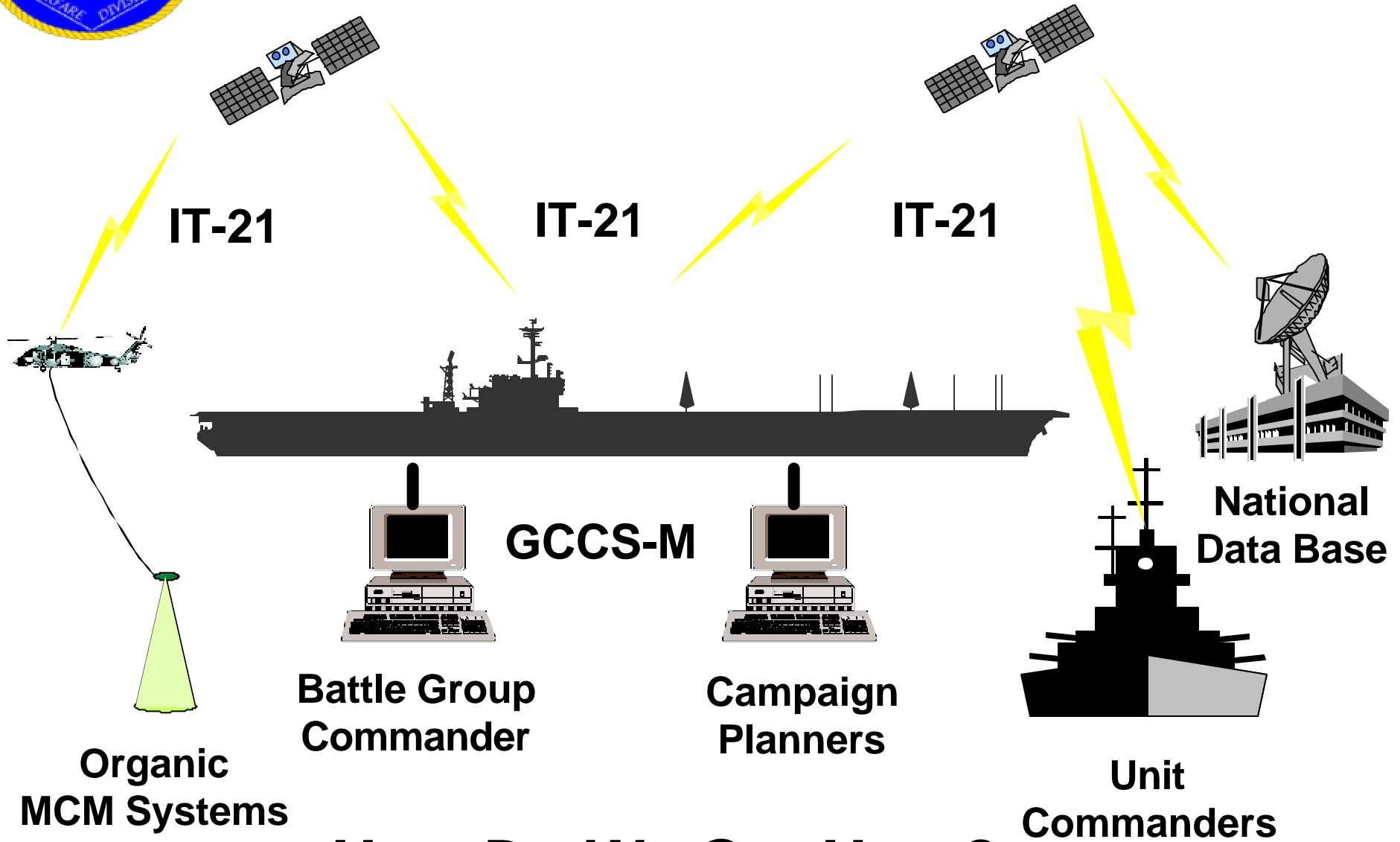
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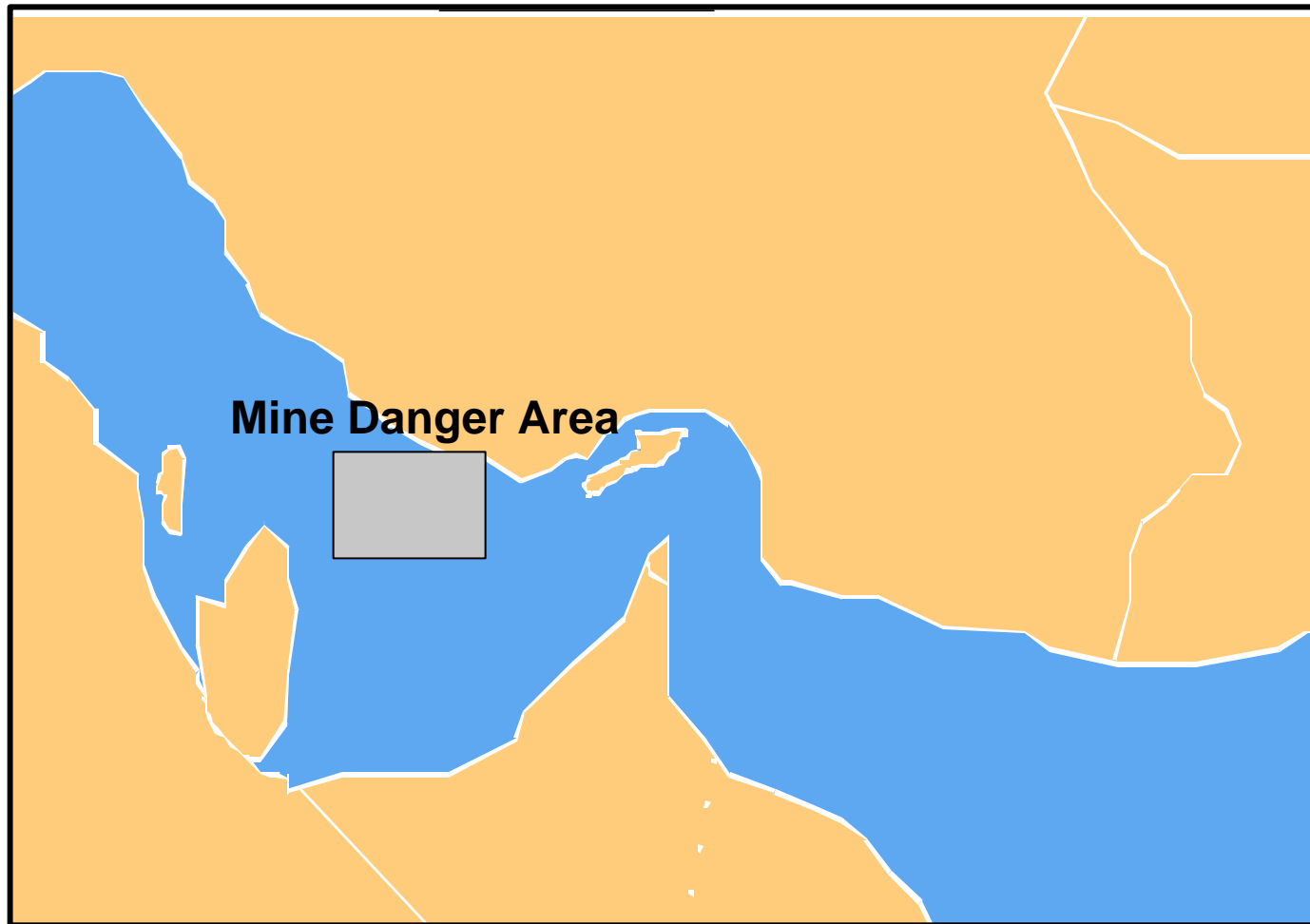
Battlegroup Centric View



How Do We Get Here?

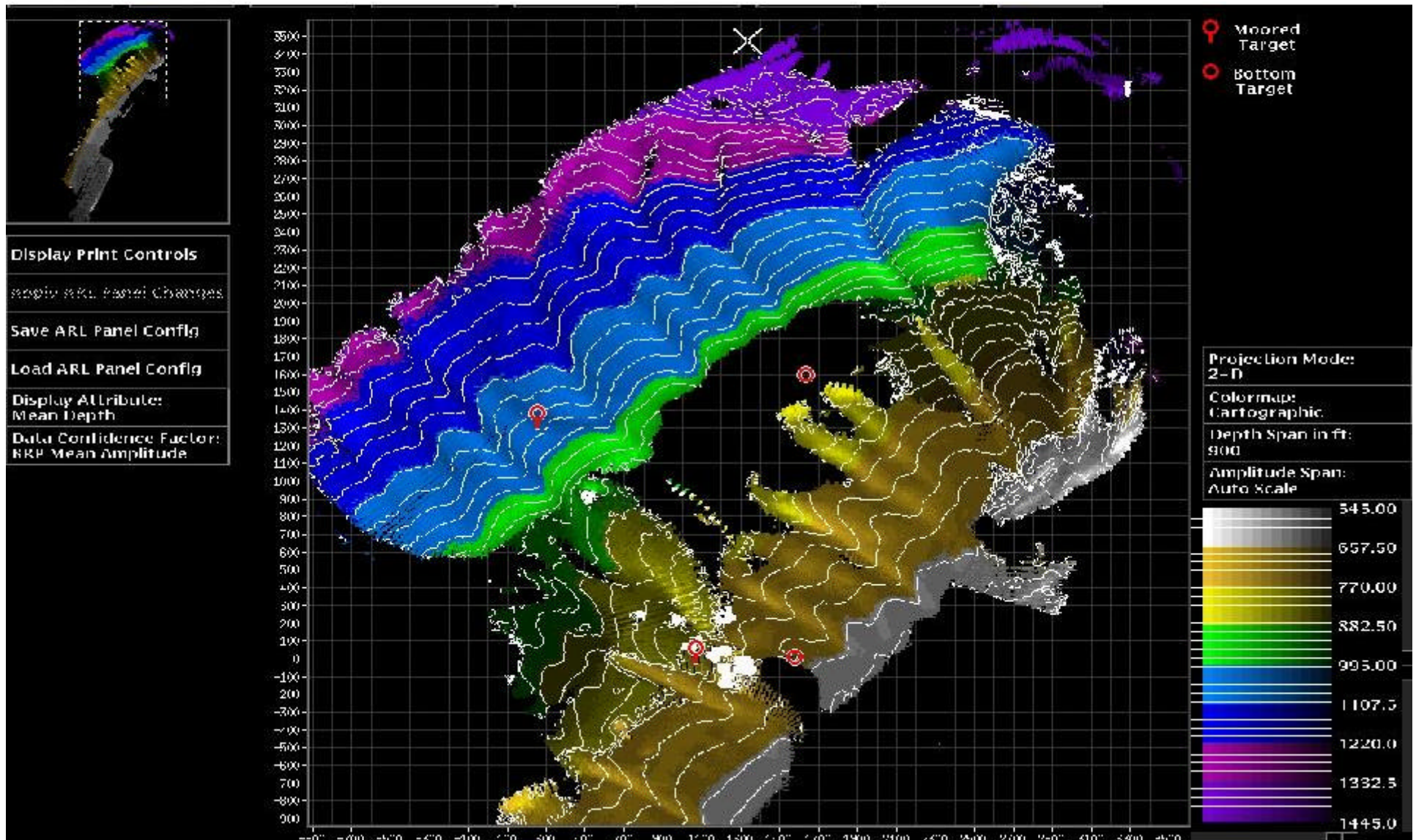


MCM COP Display Level 1



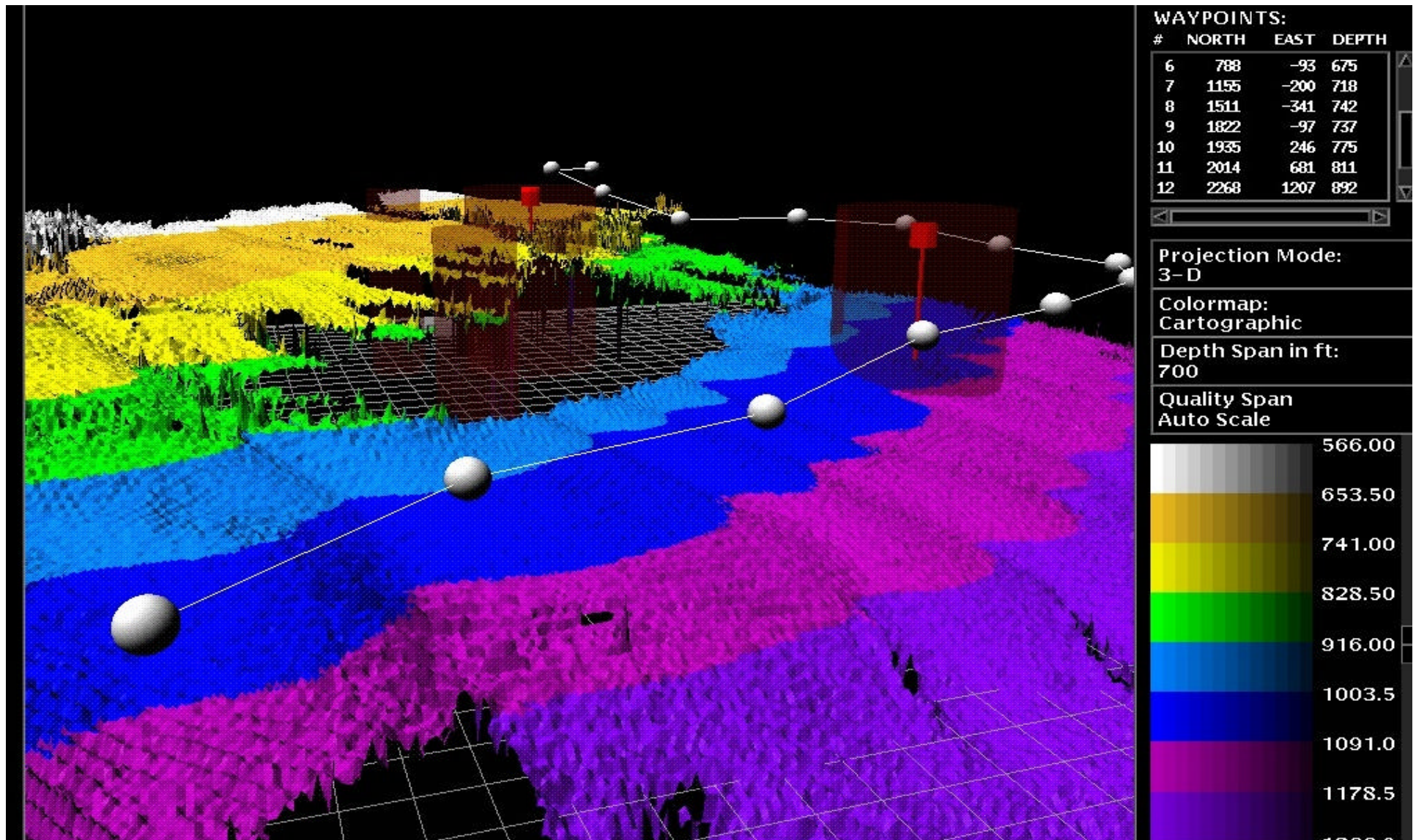


MCM COP Display Level 2





MCM COP Display Level 3



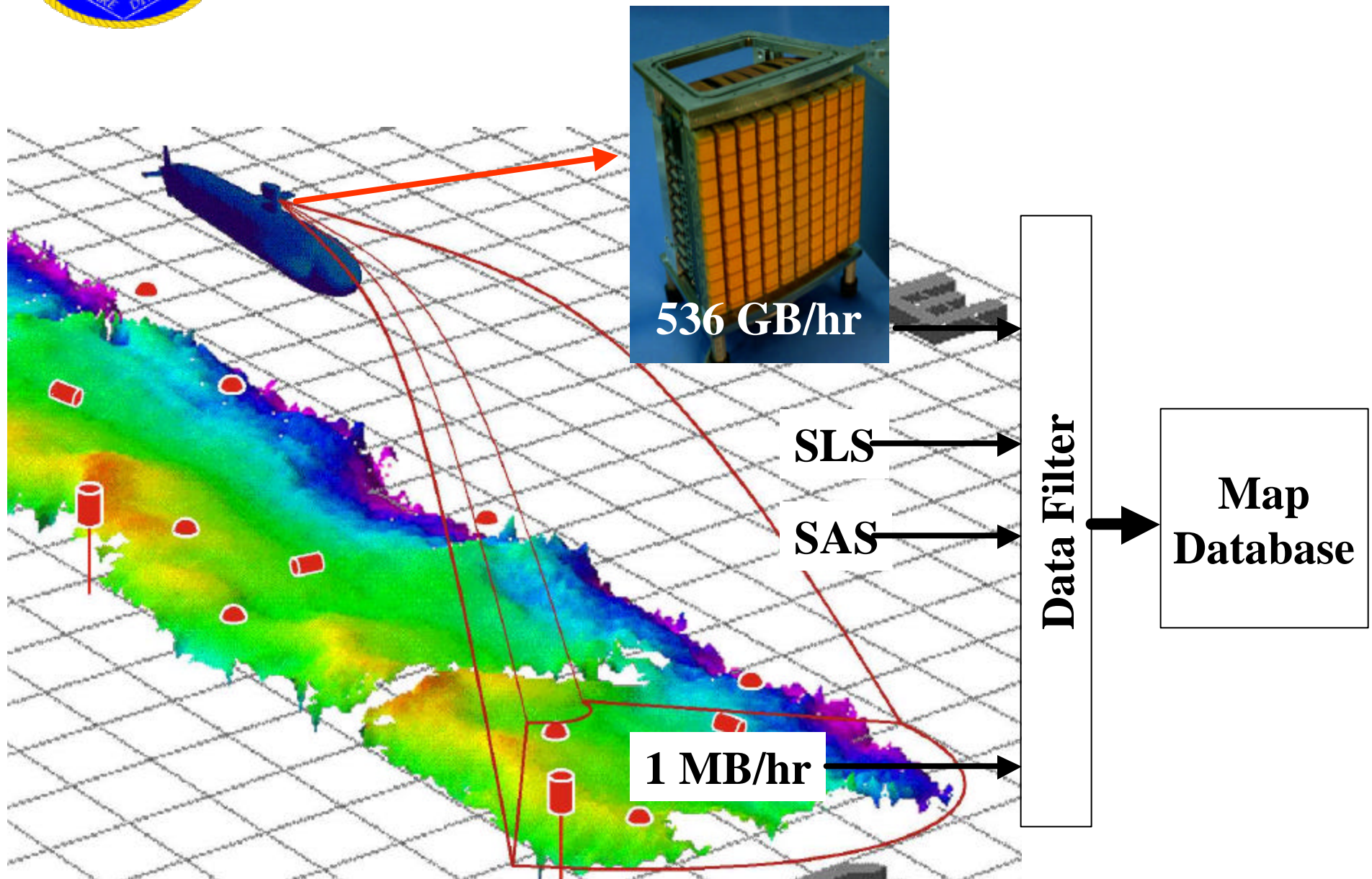


Our Proposed Solution

- **We need a common set of data standards to ensure interoperability.**
- **The Submarine Force is going forward with the production of an “Undersea Map” as the standard for data integration.**
- **A map could contain any or all of the following information:**
 - **Contact information**
 - **Environmental information**
 - **Bathymetric information**

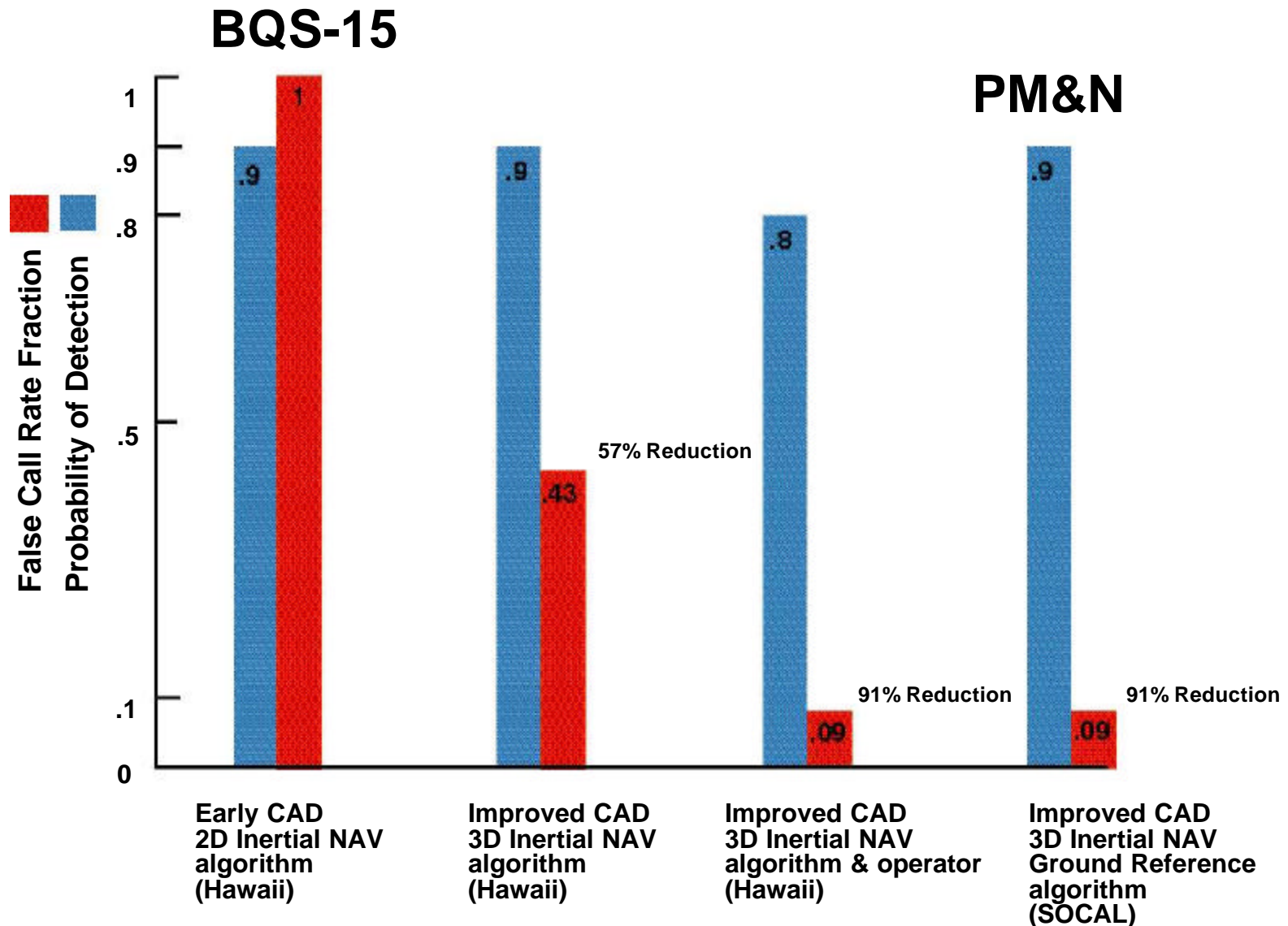


Enables Connectivity



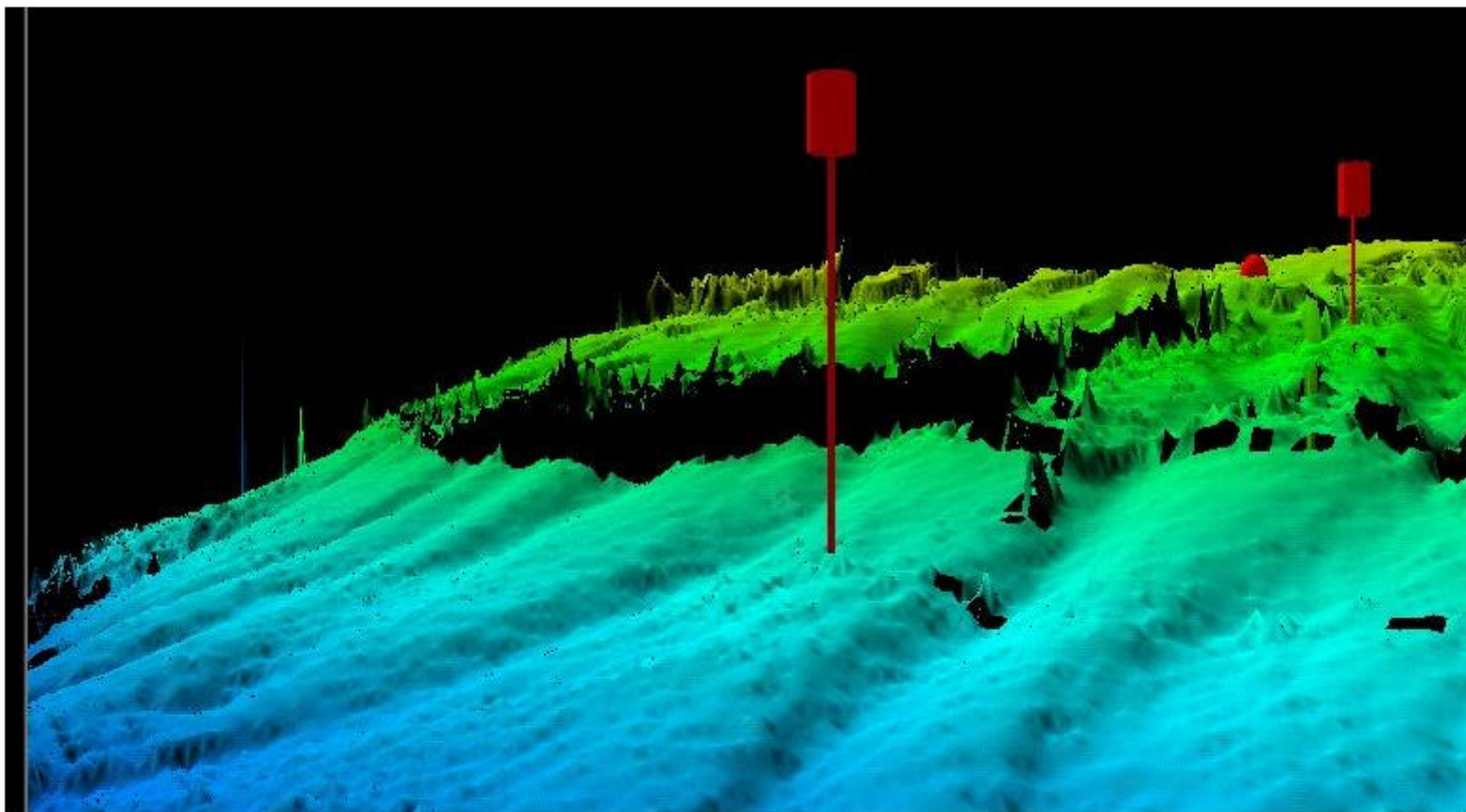


Greatly Reduced False Call Rate





Provides More Than Just Mine Locations

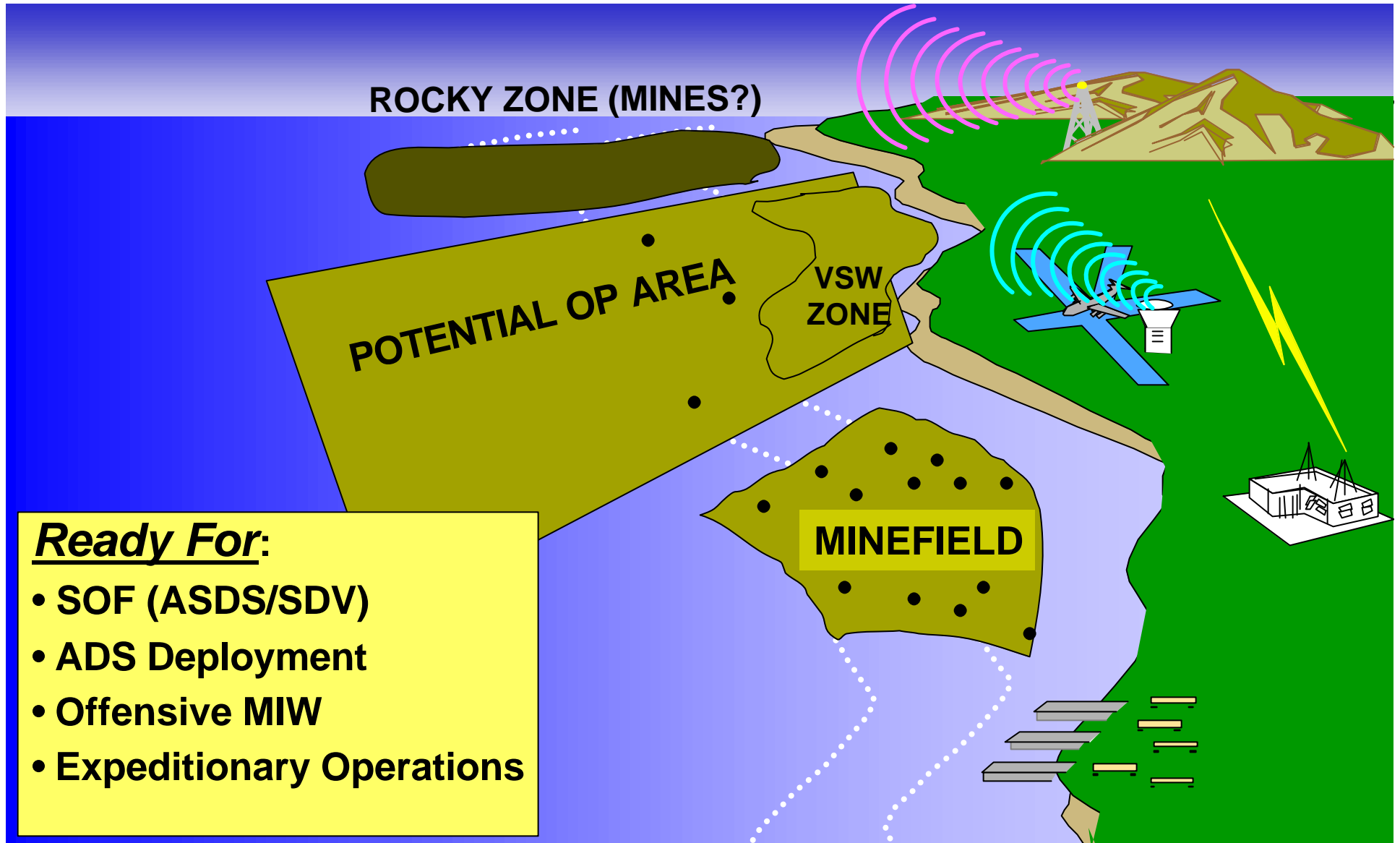


Mapping Features:

- MCM Obstacle/Contact Mapping
- Precision Bathymetry
- 2D/3D Map Visualization
- Precision Navigation
- Exportable Products



For Uses Beyond MCM





How to Reduce the Timeline?

- **Maximize the area coverage rate without sacrificing the ability to differentiate between a mine and a non-mine (increase the speed of advance, swath size or both).**
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Detect® Discriminate® Classify® Identify



Summary

- **Precision Mapping & Navigation will greatly reduce the False Call Rate for ALS.**
- **Synthetic Aperture Sonar for LMRS could provide “in stride” classification.**
- **Mapping Database and Data Standards will enable connectivity across the fleet.**